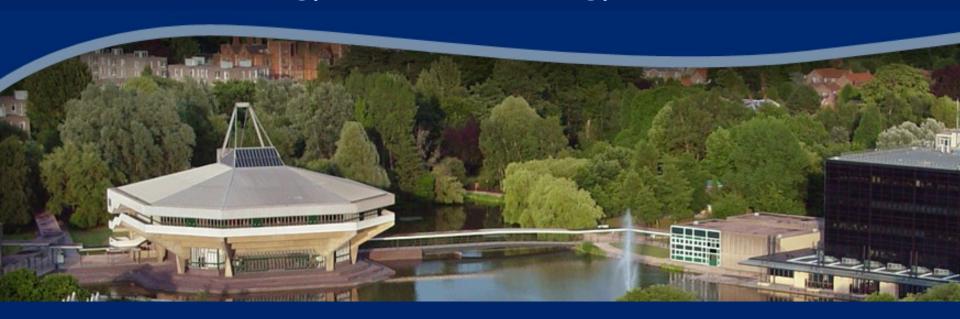
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# Cartesian Genetic Programming encoded Artificial Neural Networks: A Comparison using Three Benchmarks

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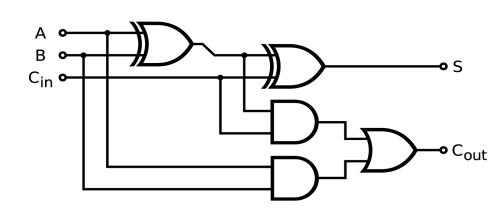
## Cartesian Genetic Programming

#### First Implemented by J. F. Miller & P. Thomson, 2000

Web page: http://www.cartesiangp.co.uk/

#### **Key Points**

- Form of Genetic Programming
- Cyclic and acyclic graphs
- Any data type e.g. ints, floats, images, videos ...
- Any function e.g. XOR, sigmoidal, sin ...
- Inbuilt neutrality and genetic drift (Miller et al, 2006)
- Natural resilience to bloat (Miller, 2001)
- Typically uses a (1+4)-ES
- Mutation only (no crossover)
- Not just for circuits





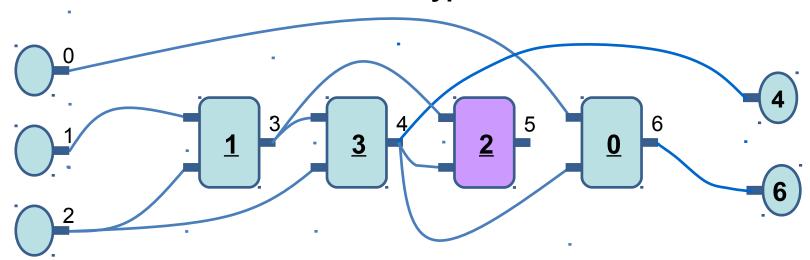
## **CGP Structure**





One row, four columns

### **Phenotype**





## **CGP** and Neural Networks

#### First published by Maryam. M. Khan et al, 2010

#### Minor changes to CGP to encode Neural Networks

• F Function i.e. sigmoid, radial basis...

• C Unchanged

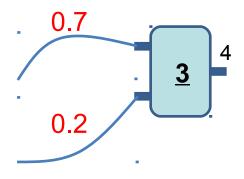
W Connection Weight

Inputs UnchangedOutputs Unchanged

#### **CGPANN** Features

- Evolves Weights
- Evolves Number of Neuron
- Evolves Topology
- Evolves Arity of Neurons (indirectly)
- Evolves Functions
- All of the advantages of CGP







## NeuroEvolution

#### **Weight Evolution**

- Does not require differentiable neuron functions
- Does not require a precise fitness function
- Does not struggle to train deep topologies
- Searches weight space

#### **Topology Evolution**

- Does not require a suitable topology to be known in advance
- Produces topologies which would not usually be considered
- Searches topology space

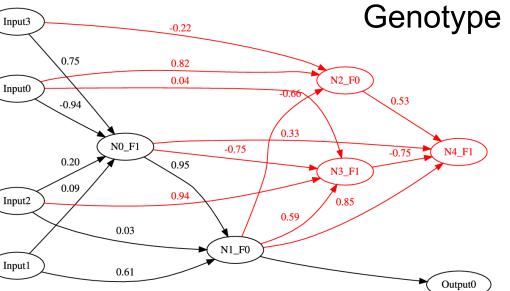
#### **Node Transfer Evolution**

- Does not require suitable node functions to be known in advance
- Can easily use a mix of node functions
- Searches function space

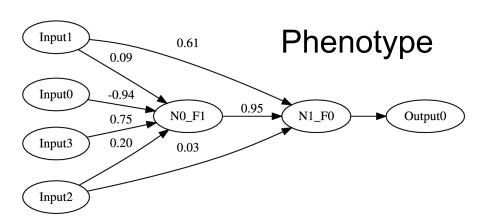


## **Inactive Nodes**





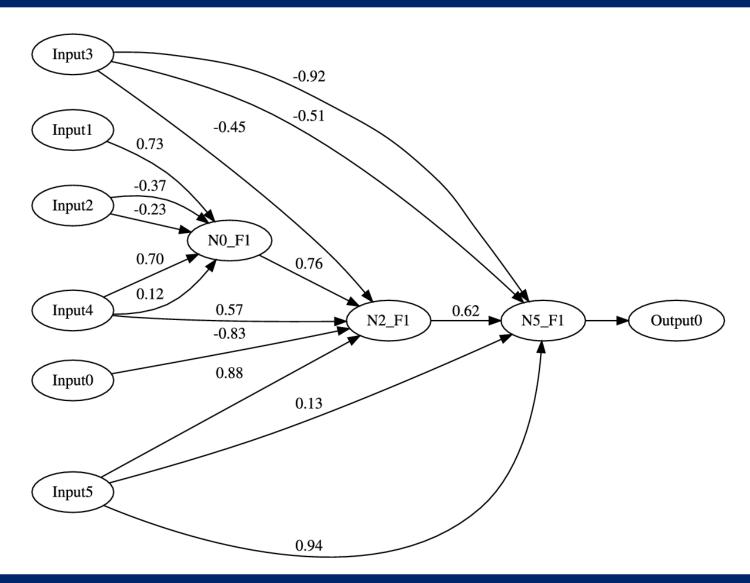
- Inactive Nodes
- Active Nodes





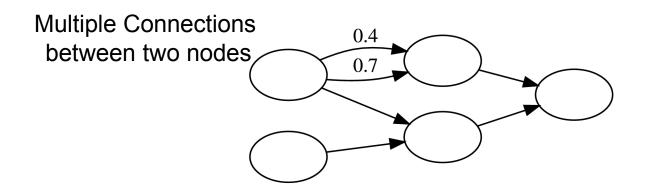


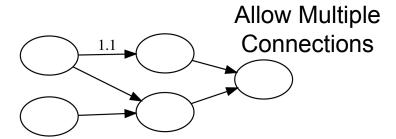


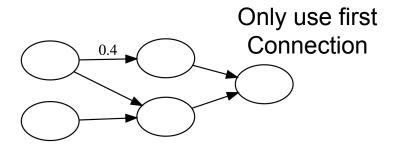


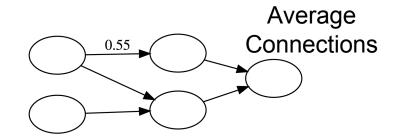


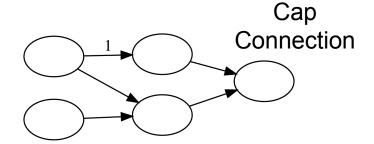
# Multiple Connections













## Benchmarks

#### **Benchmarks**

- Double Pole Balancing
- Ball Throwing
- Proben1: Cancer1

#### **Parameters**

- (1+4)-ES
- Uniform Mutation
- No Crossover
- Only Bipolar or Unipolar Sigmoid
- Allowed multiple connections between nodes

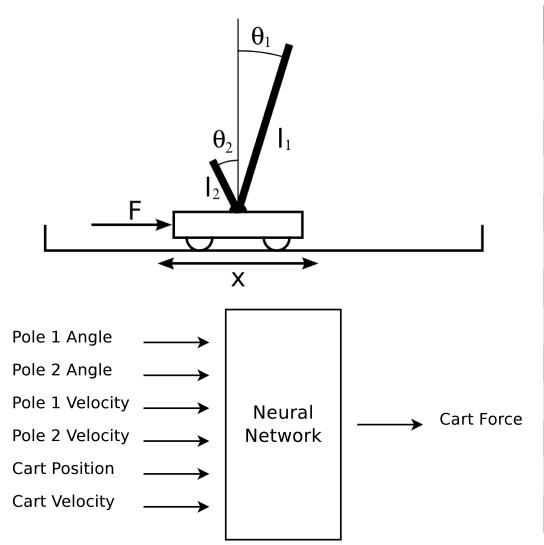
#### Comparison

- Can only use averages
- Data not available for statical significance tests





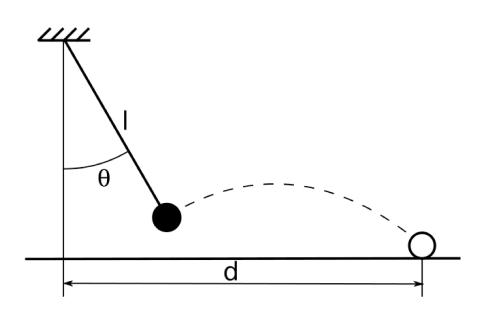
# Double Pole Balancing



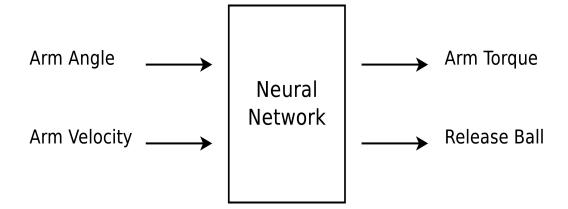
Method	Evaluations
DirE	410
CMA-ES	859
CoSyNE	954
CGPANN	1111
NEvA	2177
NEAT	3578
ESP	3800
Q-MPL	10583
SAIN	12600
EuSAIN	~19000
CNE	22100
CE	34000
EP	307200



# **Ball Throwing**

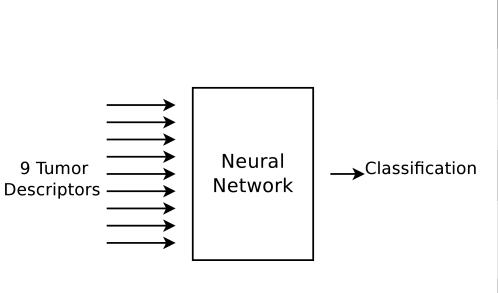


Method	Evaluations
CGPANN	6069
Compressed CoSyNE	8220
CoSyNE	10224





## Proben1: Cancer1



Method	Train Err %	Test Err %
MFN	-	1.38
M-RAN	-	1.72
CGPANN	2.68	1.89
GA-MOO- ANN	-	1.9
MFNNCA	24.86	2
ACS	-	2.184
BP	-	3.506
CMAC ANN	0.59	3.94

Data from University of Wisconsin Hospital (O. Mangasarian et al, 1990)

Following the Proben1 Document (L. Prechelt, 1994)





#### **Overall:**

CGPANN is a highly competitive NeuroEvolutionary strategy which assumes very little about the structure of the neural network to be evolved.

#### Take Home Message:

CGPANN directly evolves the weights, number of nodes, topology, and nodes function of artificial neural networks. CGPANN also indirectly evolves the arity of each node. Additionally CGPANN has all of the benefits of CGP; natural resilience to bloat and neutrality in the genotype aiding evolution through genetic drift.



## Questions

